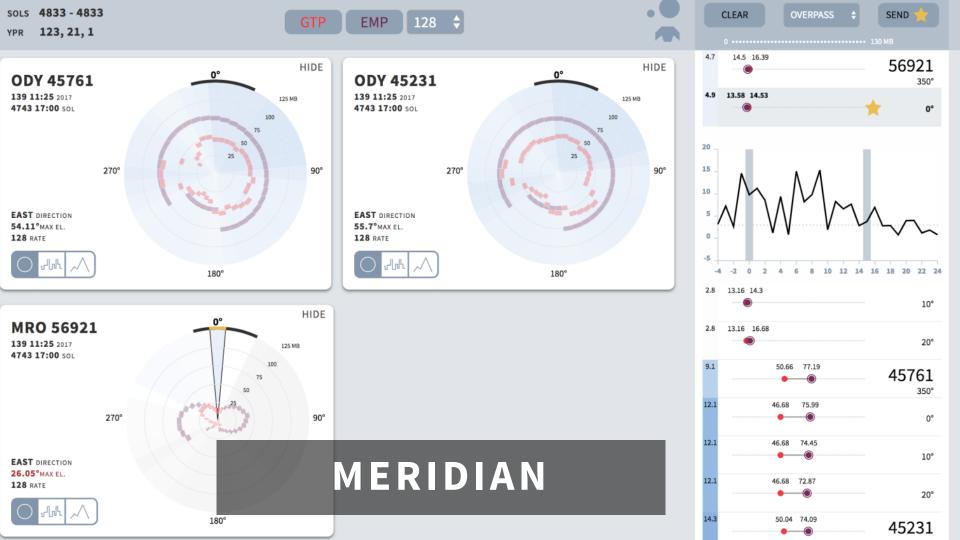
## MERIDIAN

MARS EXPLORATION ROVER TELECOM PREDICTION

MATT CONLEN CHELLY JIN SARA STALLA

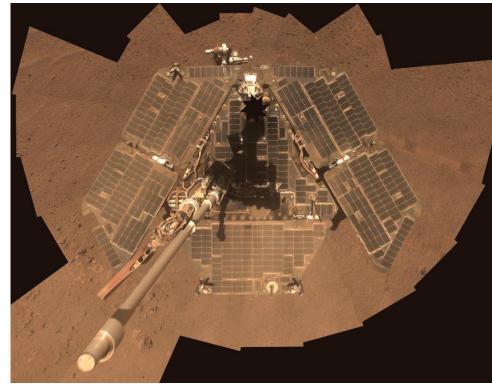
**PI: VICKIE SCARFFE-BARRETT** 



# Mars Exploration Rover (MER) **OPPORTUNITY**

Launched in 2003, on Mars since 2004

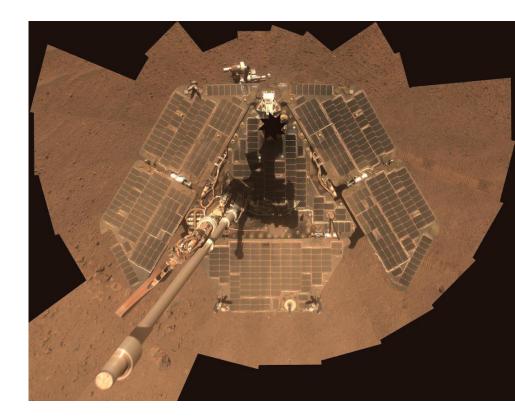
Several cameras onboard spectrometer microscopic imager



Mission was meant to last 90 days, certain tools not developed for long term management

#### **ROVER LIMITATIONS**

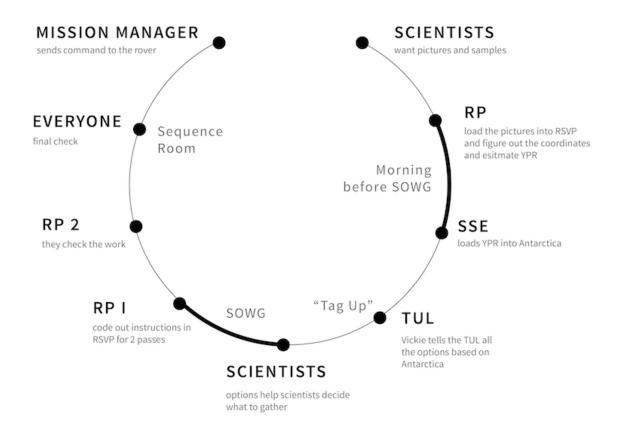
steering, driving, memory is wiped every night

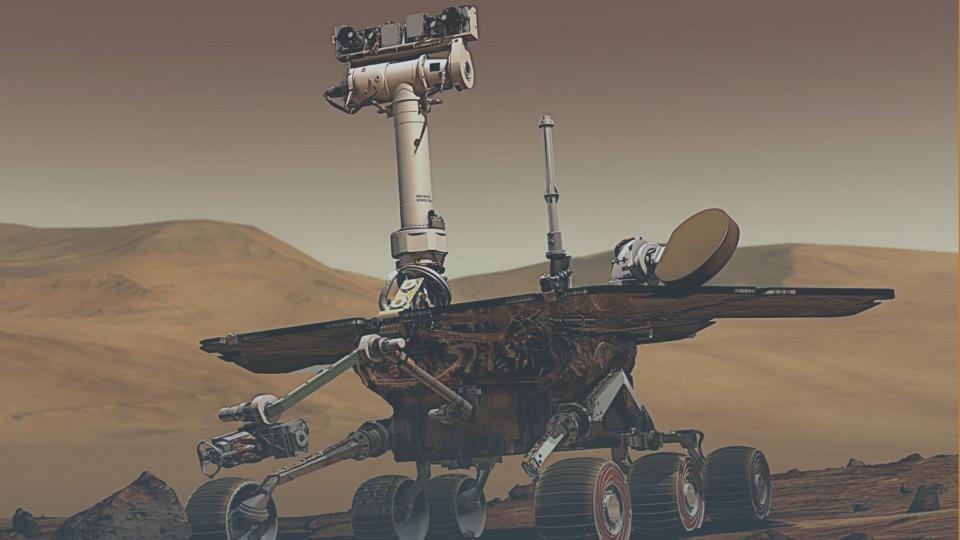


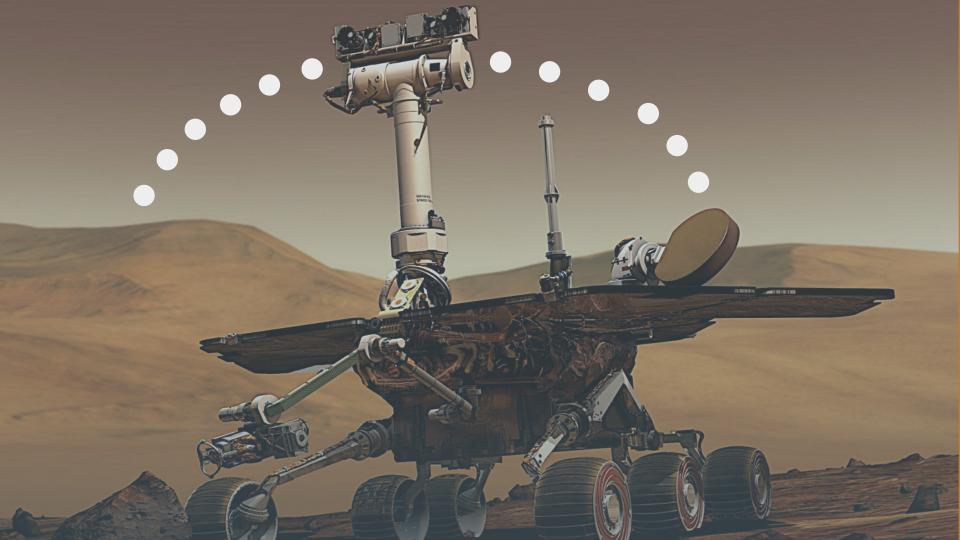
### **PROBLEM STATEMENT**

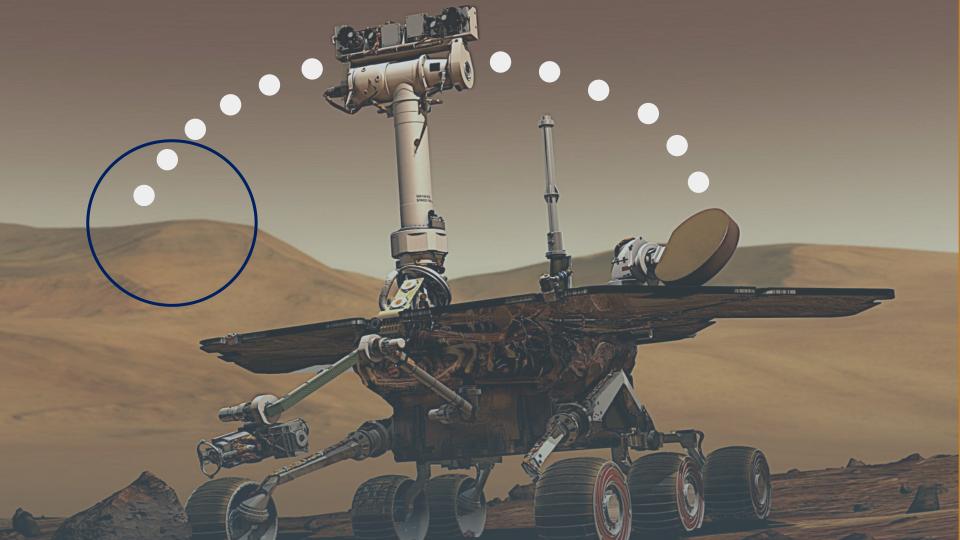
Spacecraft Systems Engineers (SSEs) need to prediction how much data can be transferred from the rover to an overpassing satellite in order to:

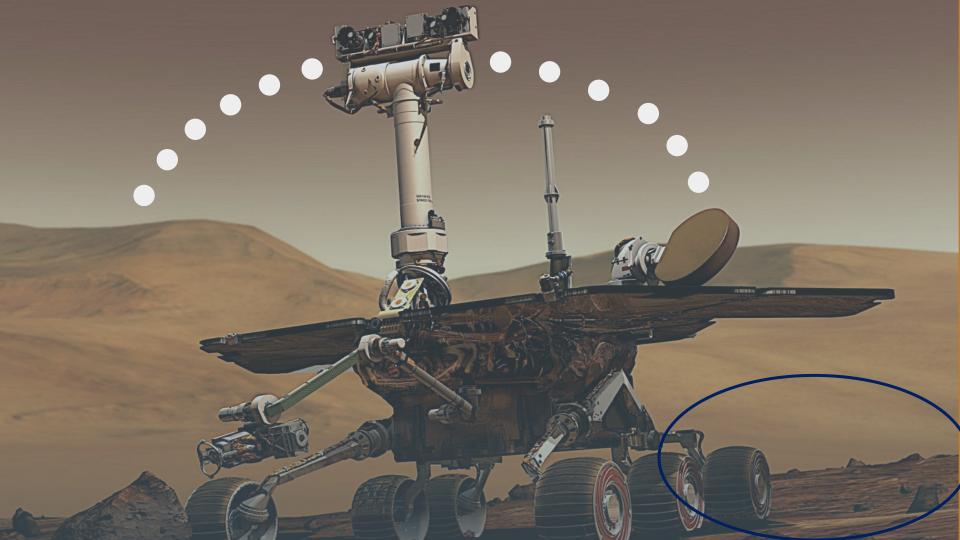
- 01 Provide scientists with an estimate of available data transfer
- 02 Recommend the heading at which a rover should end its path to achieve a high level of data transfer.

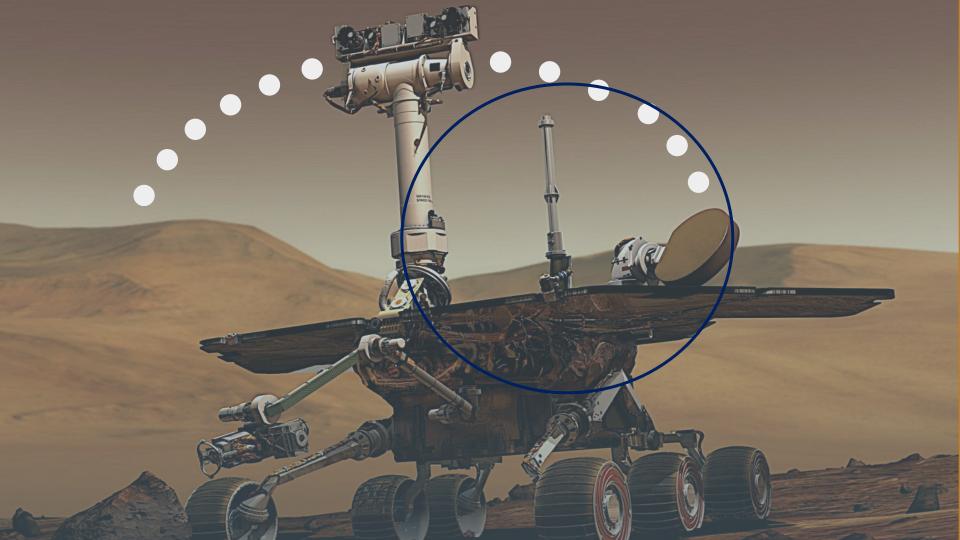






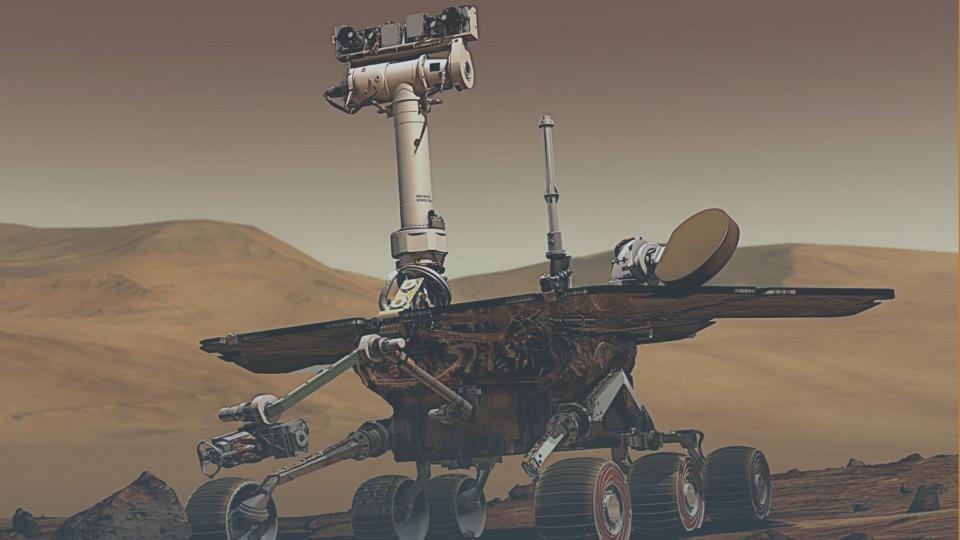






## WHEN MAKING DECISIONS ABOUT DATA TRANSFER, **SSEs MUST CONSIDER**

01 The ability of the rover to link with the orbiter <u>Link Margin</u> 02 The total amount of data that can be transferred <u>GTP</u> <u>EMP</u>



"Currently our method of evaluating our heading choices is to open all of the plots, on different computers or windows, and to examine each one, moving them around the screen to compare next to each other.

Sometimes we will even print out some of the plots and hold layered paper up to the light to compare them together."

#### \* \* \* W A R N I N G \* \* \* You are connected to a Jet Propulsion Laboratory machine

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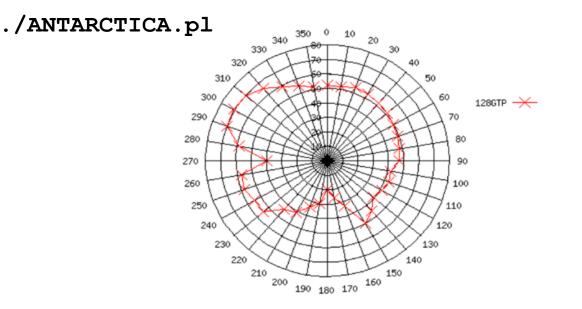
Unauthorized Access is a violation of U. S. Federal Law.

\* \* \* W A R N I N G \* \* \*
You are connected to a Jet Propulsion Laboratory machine

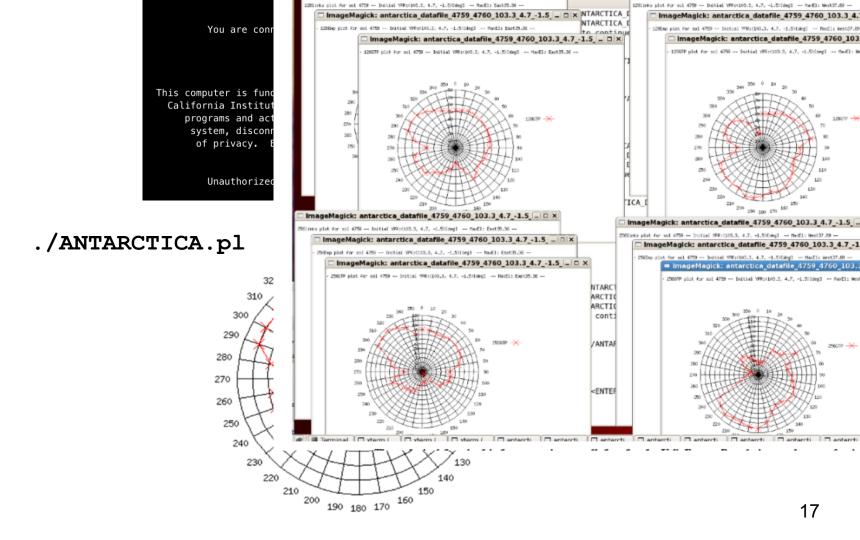
Property of the UNITED STATES GOVERNMENT

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16

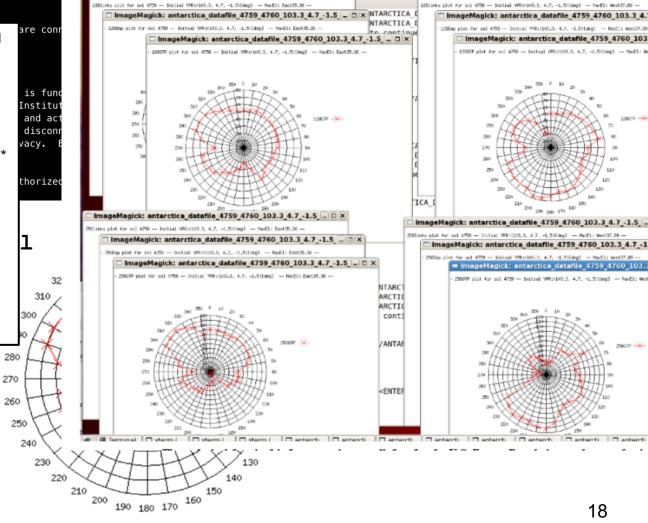


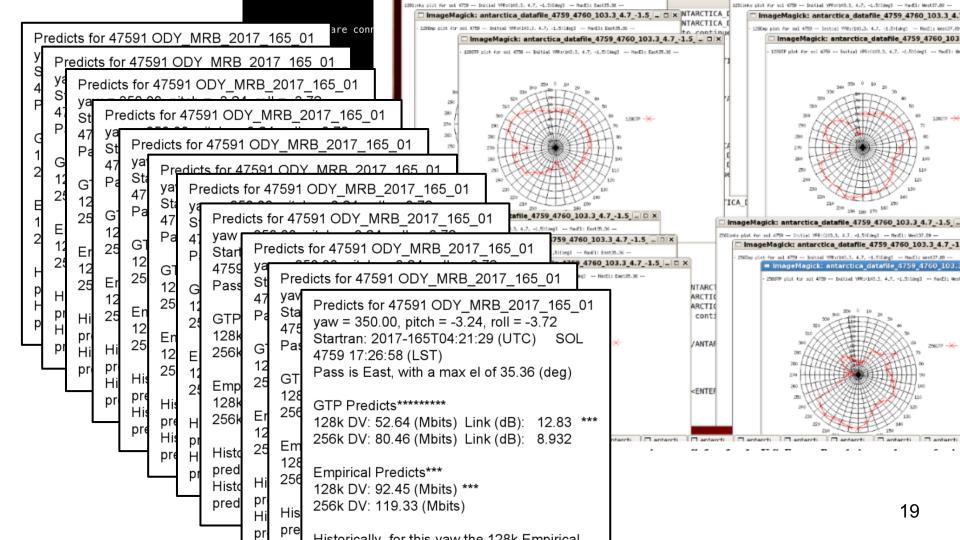
Predicts for 47591 ODY\_MRB\_2017\_165\_01 yaw = 350.00, pitch = -3.24, roll = -3.72 Startran: 2017-165T04:21:29 (UTC) SOL 4759 17:26:58 (LST) Pass is East, with a max el of 35.36 (deg)

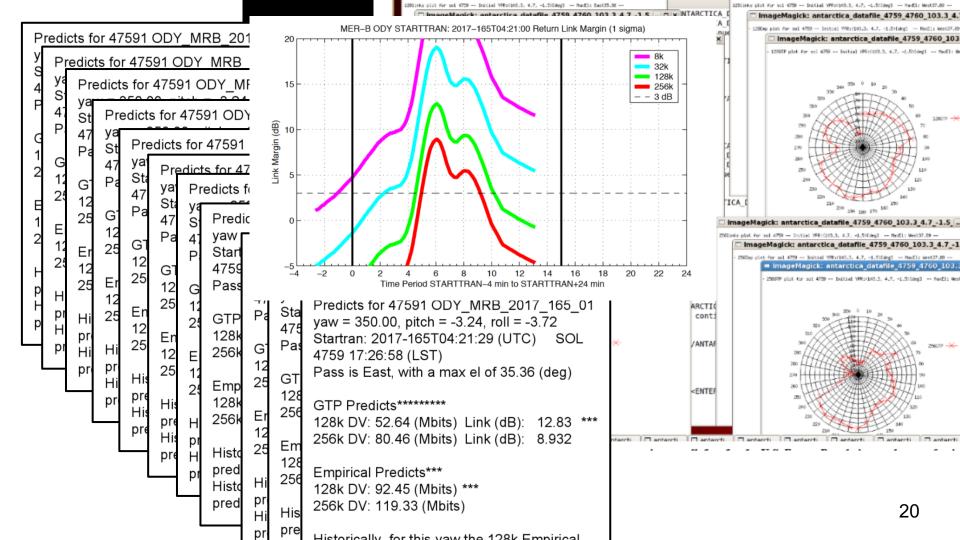
GTP Predicts\*\*\*\*\*\*\*\* 128k DV: 52.64 (Mbits) Link (dB): 12.83 \*\*\* 256k DV: 80.46 (Mbits) Link (dB): 8.932

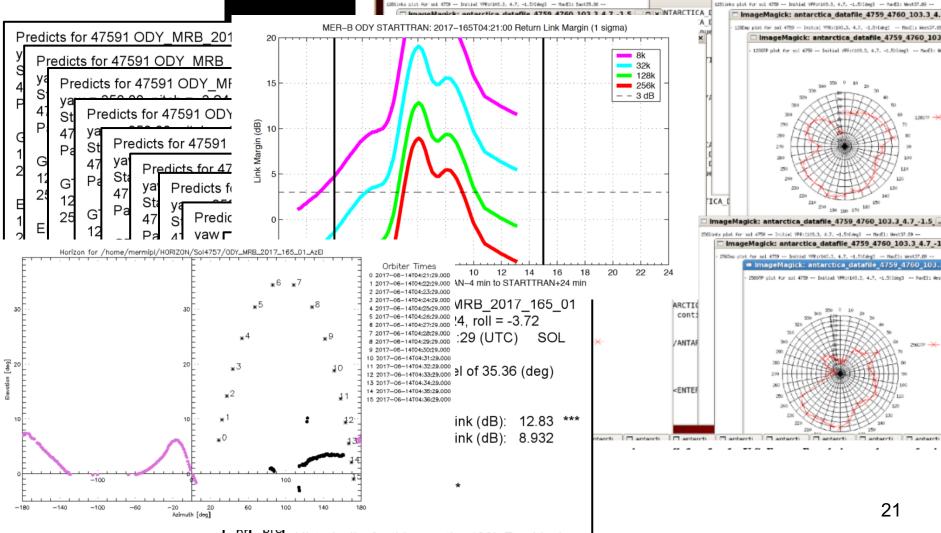
Empirical Predicts\*\*\* 128k DV: 92.45 (Mbits) \*\*\* 256k DV: 119.33 (Mbits)

Historically, for this yaw the 128k Empirical predicts have been more accurate. Historically, for this yaw the 256k Empirical predicts have been more accurate.

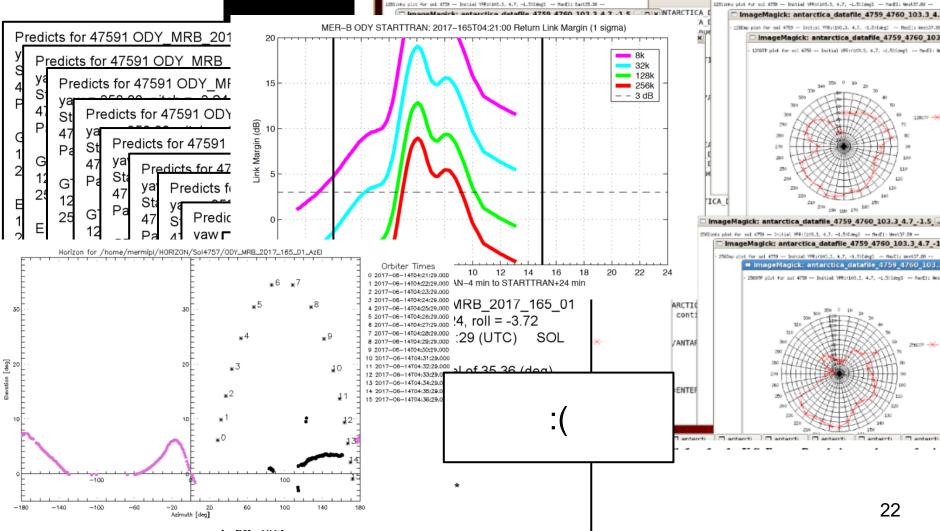








PI Historically for this yaw the 128k Empirical



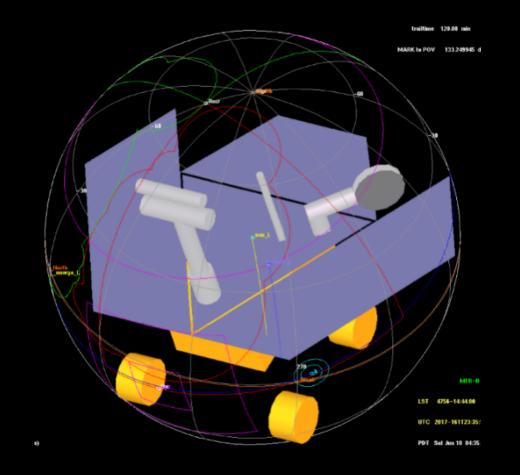
Pr Historically for this yow the 128k Empirical

### WHAT ARE THE PROBLEMS WITH THE CURRENT APPROACH



## WHAT ARE THE PROBLEMS WITH THE CURRENT APPROACH

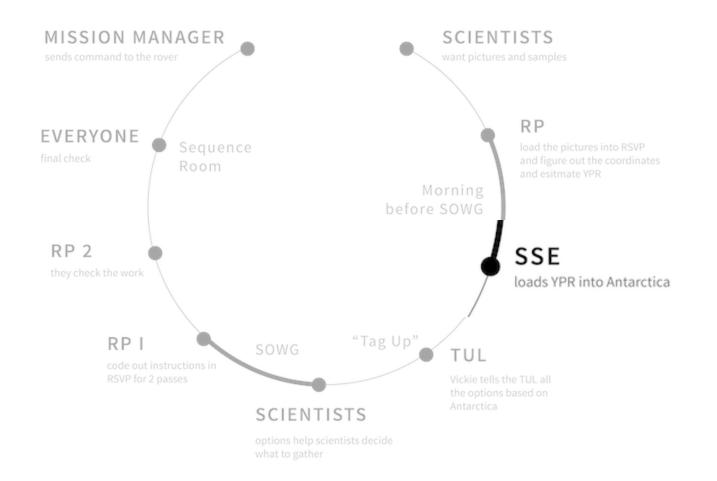
### **SERIOUS REPERCUSSIONS FOR MISTAKES**



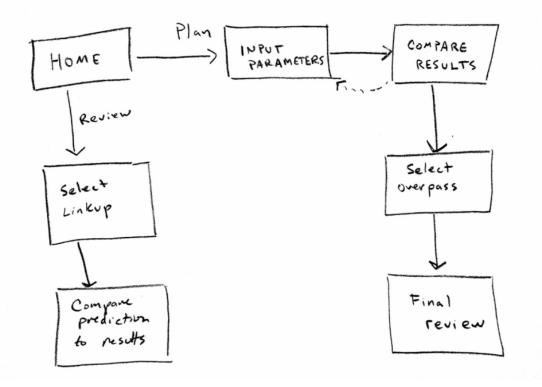
### **PROBLEM STATEMENT**

Spacecraft Systems Engineers (SSEs) need to prediction how much data can be transferred from the rover to an overpassing satellite in order to:

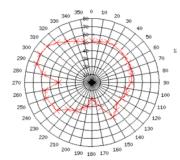
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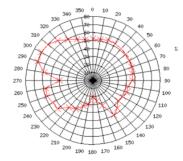


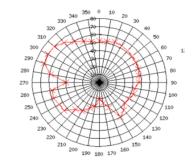
### SYSTEM WORKFLOW



### **REDESIGNING THE PLOTS**







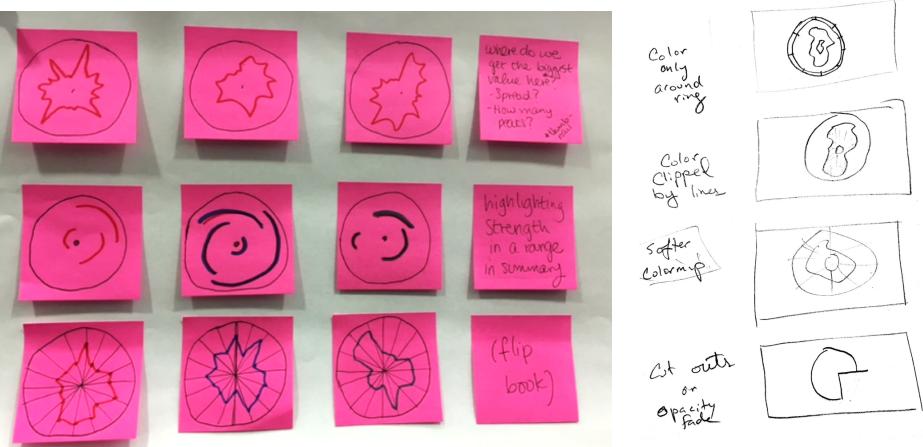
GTP

EMP

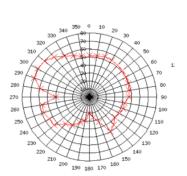
LINK MARGIN



### **REDESIGNING THE PLOTS**

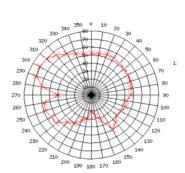


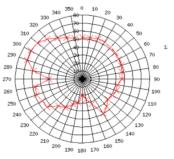


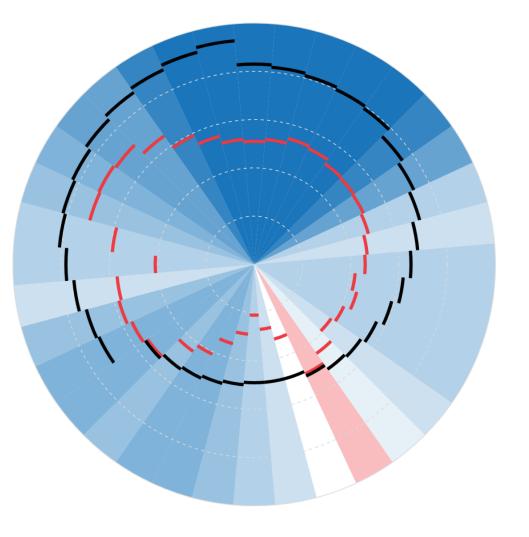




GTP













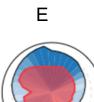














Н

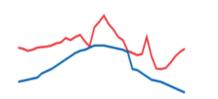




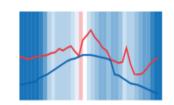




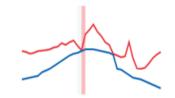




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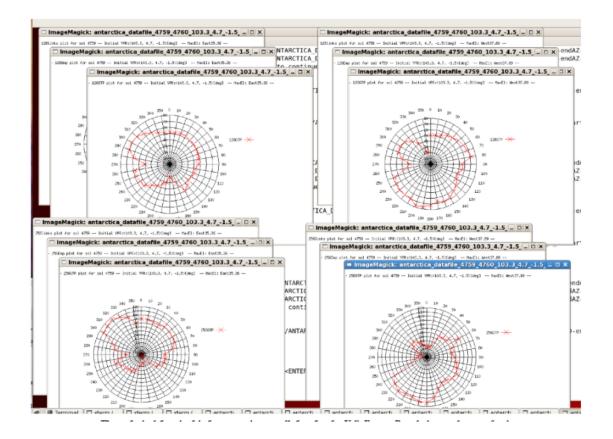
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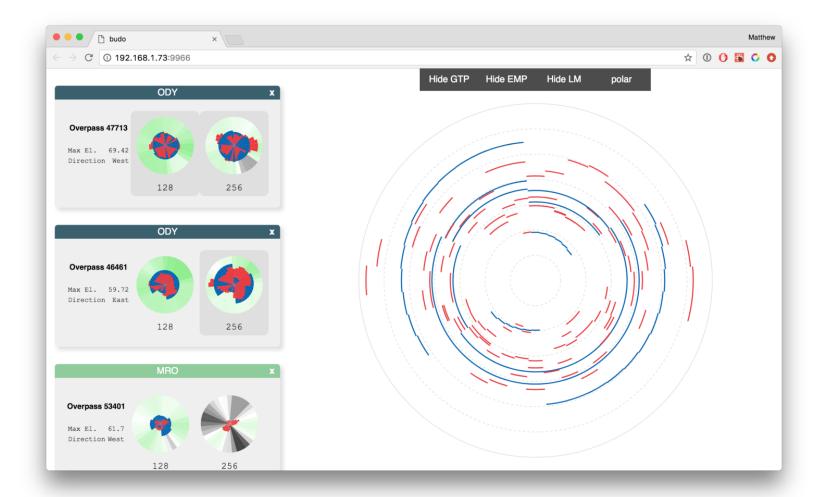
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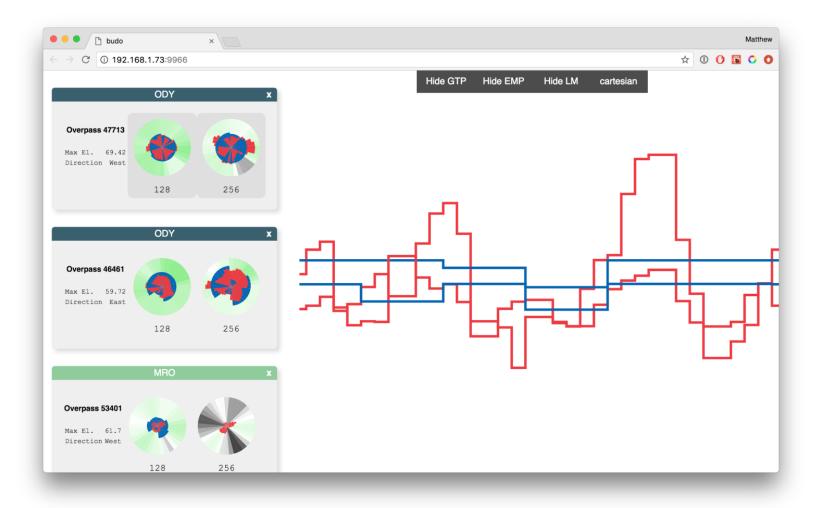
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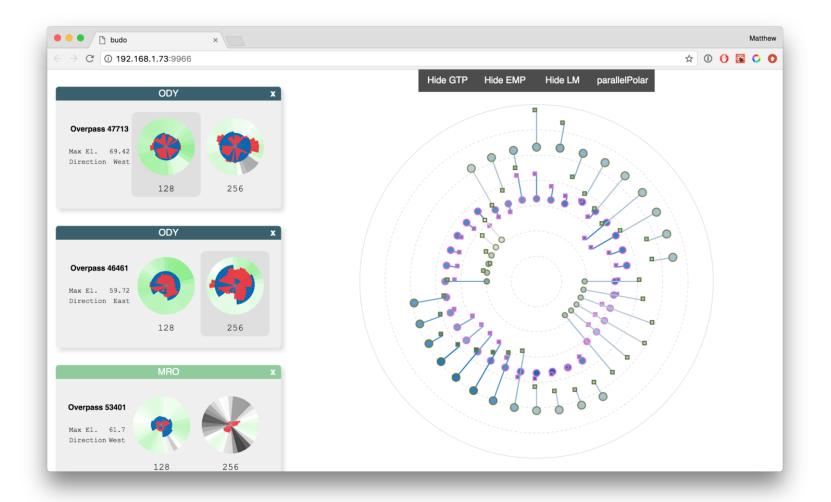
33

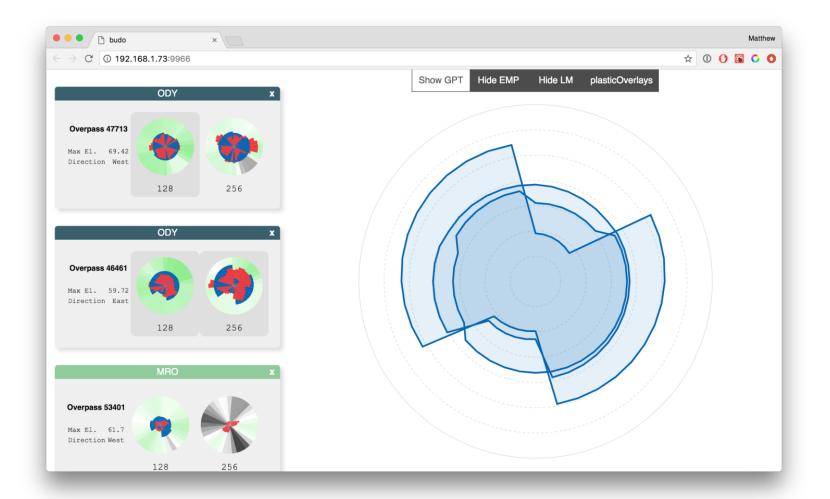
### BUT, WE STILL HAVE TO WORK WITH THIS

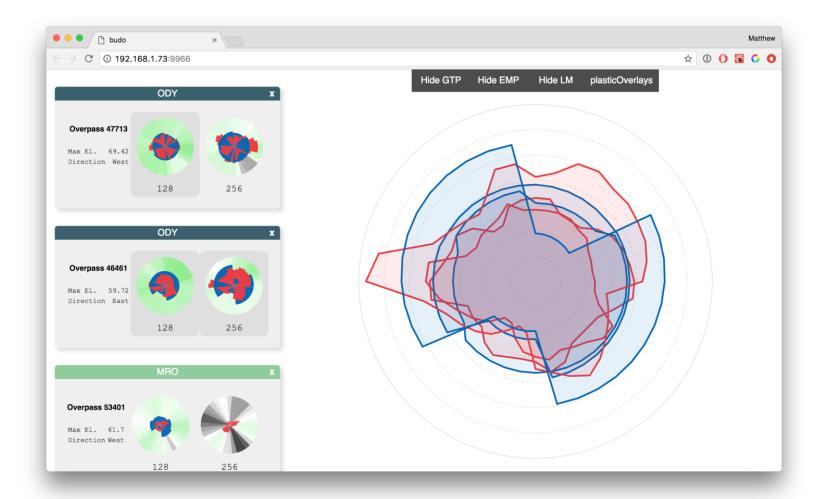


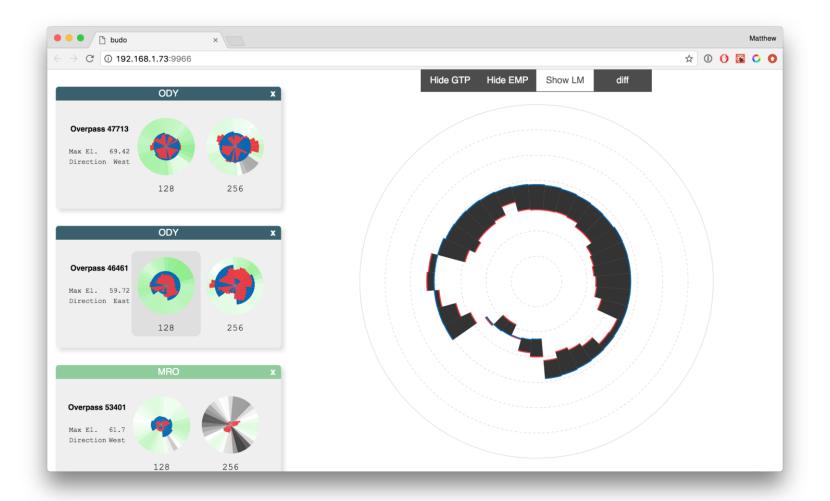


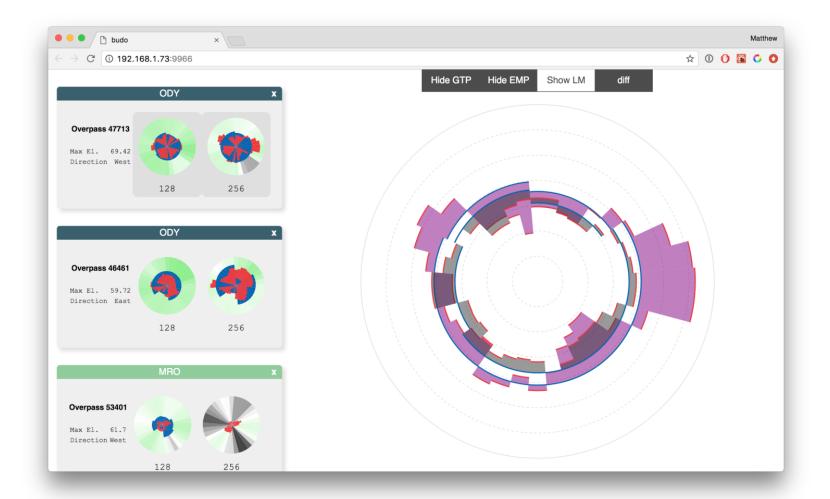


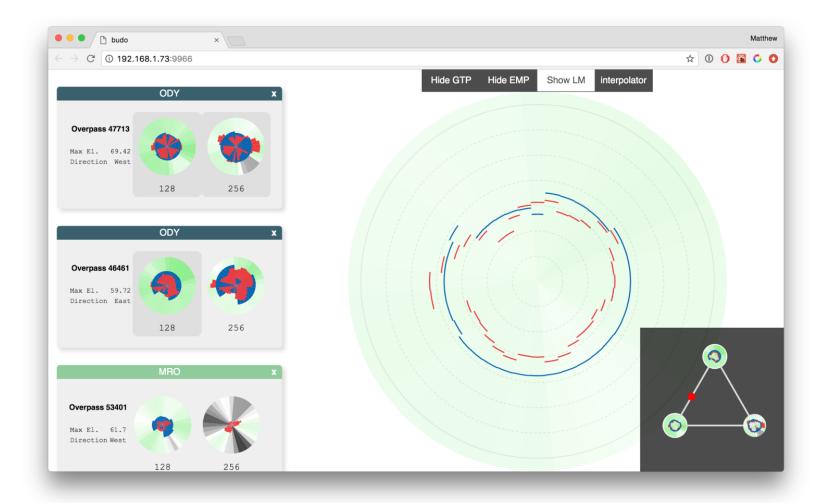


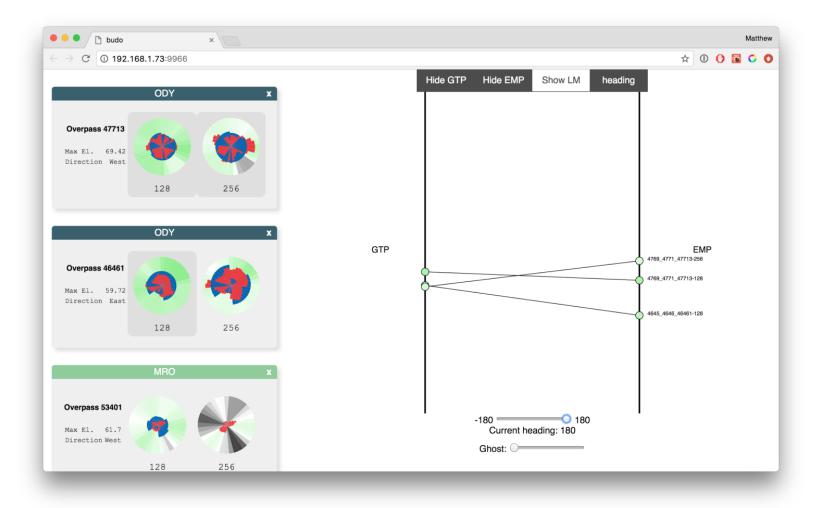


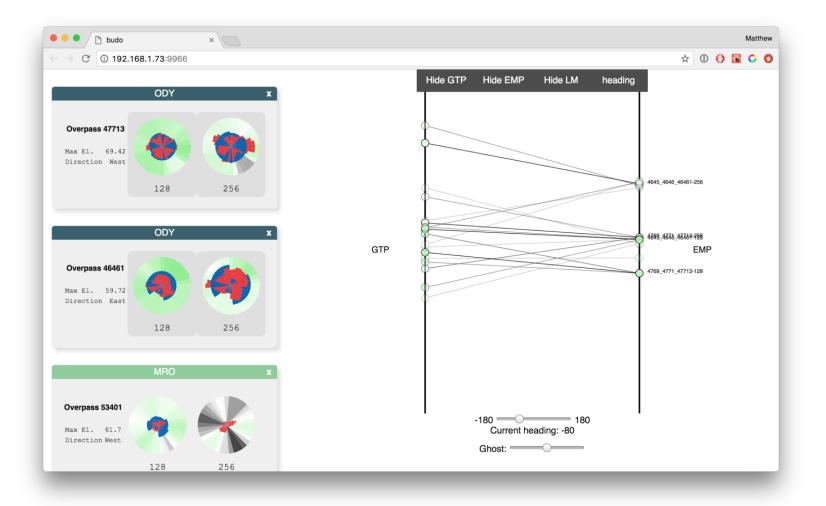


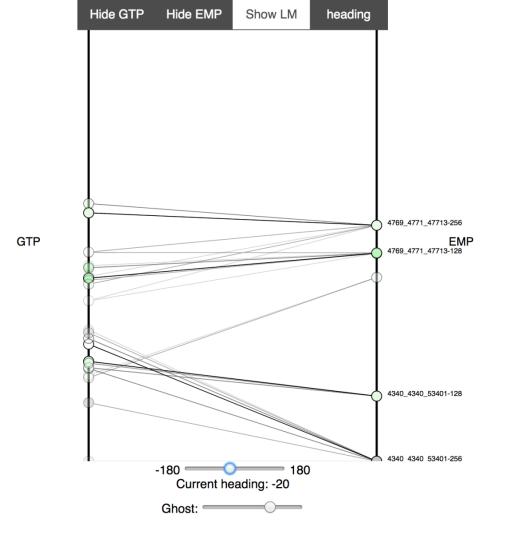




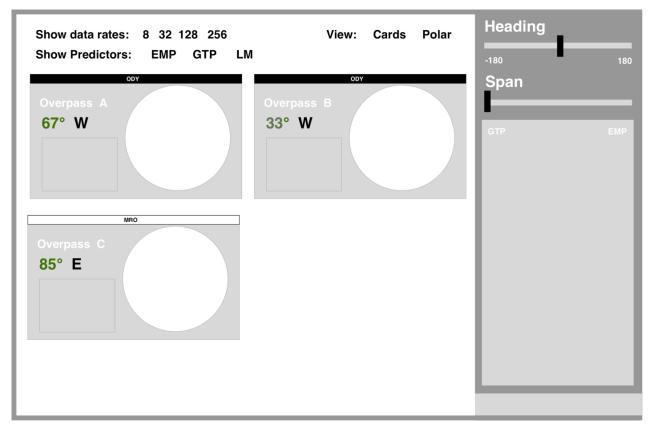


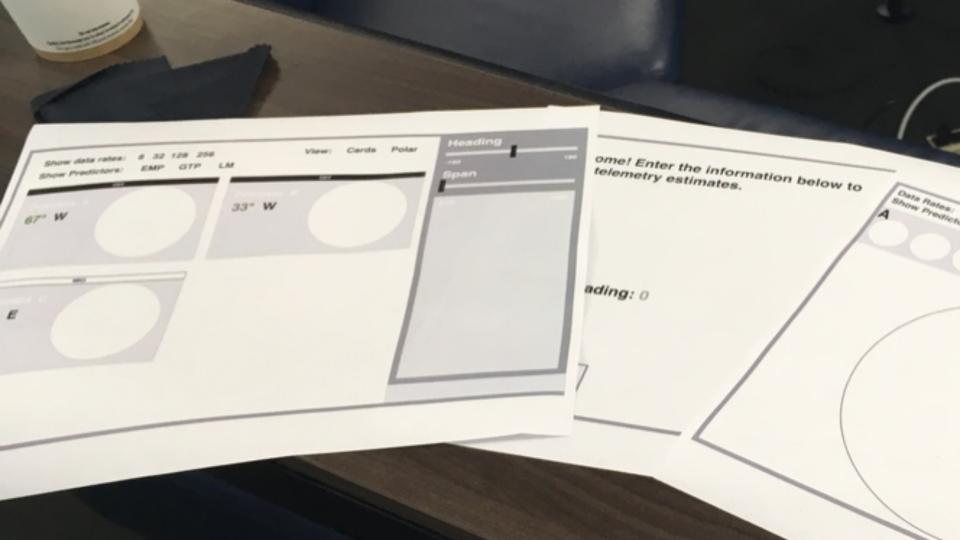


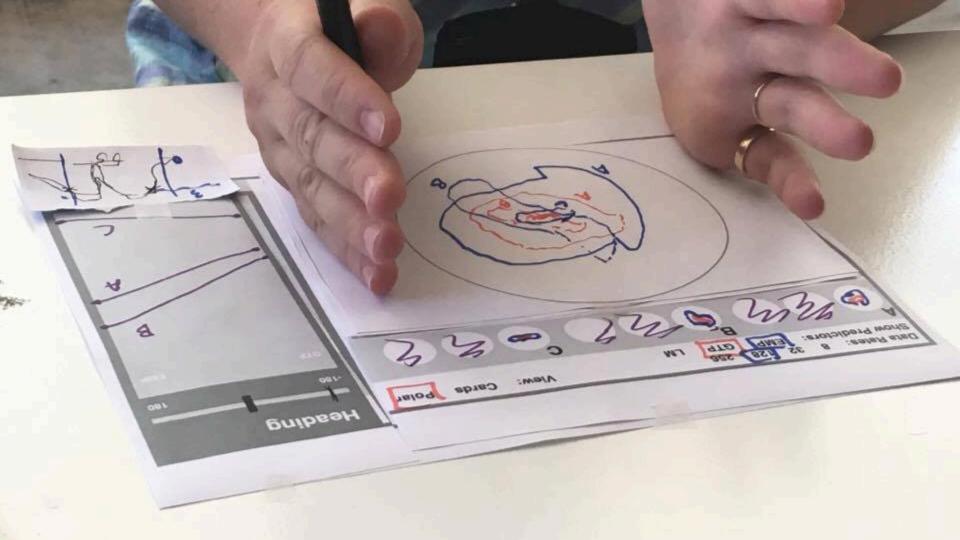




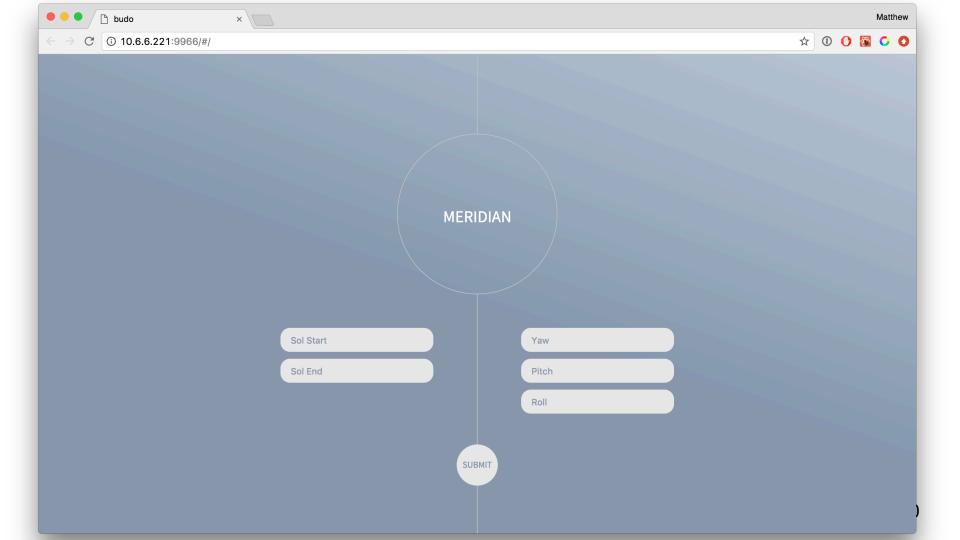
### **PAPER PROTOTYPING**







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# **OUR SOLUTION**

- 01 A centralized web interface
- 02 Organized, hierarchical info
- 03 Easy to download and send to colleagues
- 04 Plan in place to deploy with MER team

# TECH

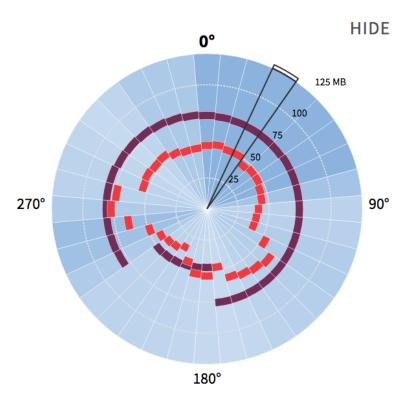
Budo development server

Flexbox for layout

**D3** for scales, calculations, colors

**React** for state & view management

Developed reusable components



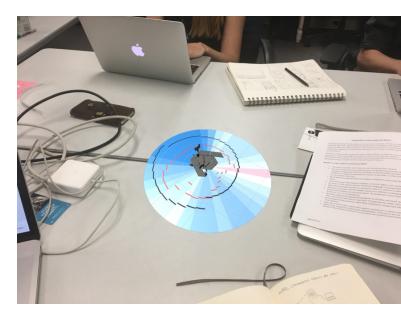
# **FUTURE WORK**

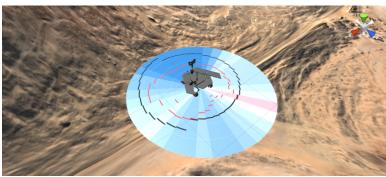
Integration into other systems Quill, 2020, etc

Integration of the rover itself in terrain mask

Mobile

3D environment





# THANK YOU

Matthew Conlen Chelly Jin Sara Stalla *PI* Vickie Scarffe-Barrett *Mentors* Scott Davidoff Maggie Hendrie Santiago Lombeyda Hillary Mushkin *Students* Fred Hohman Beatrice Jin

